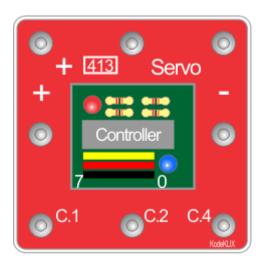




Servo Module for Robotics

Quick Start Guide



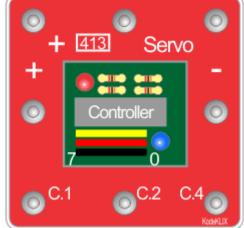


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Introduction

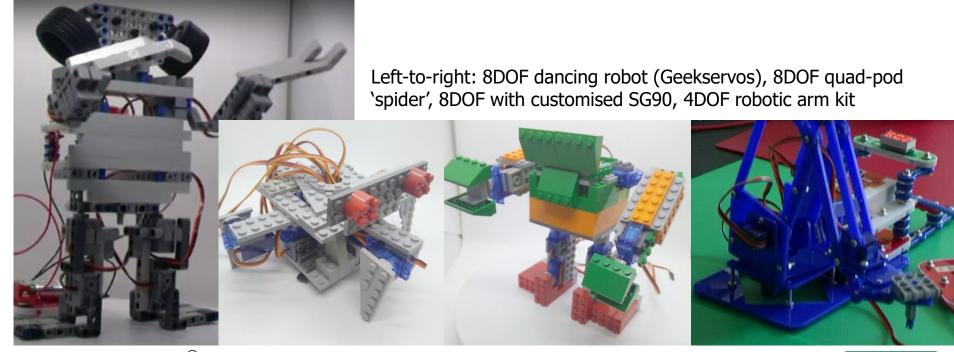
coders

- The KodeKLIX® servo module has the ability to control up to 8 standard servo motors simultaneously and jitter free
 - Simple one block command required from the SnapCPU to update all 8 servos
 - Using variables to store and change position makes this easy for both young or inexperienced
 - Standard connector means freedom to choose servos



What sort of Robotics?

The standard SnapCPU can power and control up to three servos; serious robotics normally calls for four or more degrees-offreedom (DOF, aka servo motors)



Power & Configuration

Servos use a lot of power and so a 4.5V battery pack is a must!

Power connections are located to align with the [70] battery pack

The SnapCPU20 or SnapCPU08 can readily be stacked on top

of the servo module 'arduino style'; even the ultrasonic module can be stacked and powered from the motor drivers





■ The standard SG90 is a popular design, but quality can vary between. suppliers

Geekservo make a nice 'Lego compatible' servo

> grey is 270° positional; others are 360° rotational

Customised 'Lego compatible' SG90 can be made with real Lego parts and glue

Servo Module Coding Blocks

 Variables W0-W7 correspond to varA through varH in Blockly

 Initialise these as the first step to reserve them for your robotic code

Use the Send data BLOCK
 to update the module

```
start

call initialise

to update the module

Send data [w0-w7] to KodeKLIX Servo Module C.1

wait for 1 Second(s)

**sends all 8 variables to the servo module via snap C.1

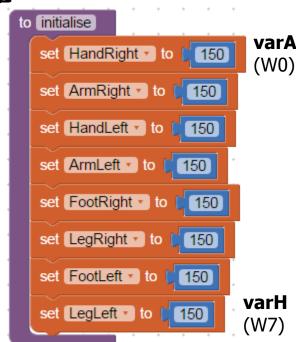
forever

do call Shuffle

call HandDance

call ArmDance

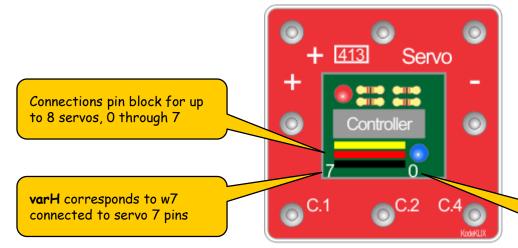
call FootDance
```

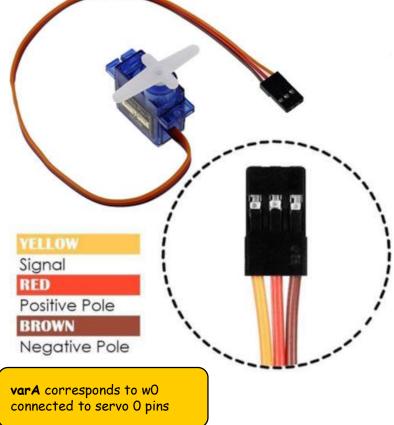


Connecting to the Module

Regardless of the servo type, they nearly all come with three (3) wires (see table)

Wire	Purpose	Type 1	Type 2
Signal	Data	Yellow	White
Positive	+V, Power	Red	Red
Negative	Ground	Brown	Black

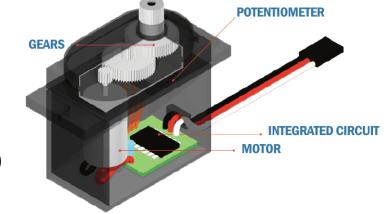




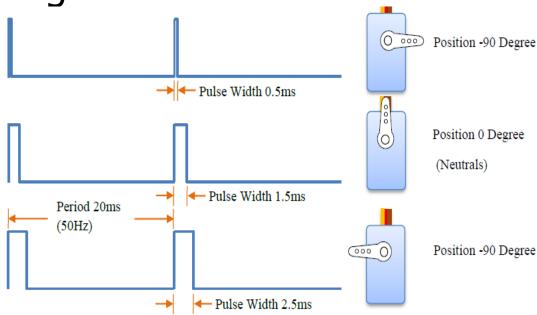


More about Servo Controls...

Inside the servo unit is a small computer that translates SERVO commands pulses into motor control signals



Giving the servo the wrong pulse signal could make it lose control!

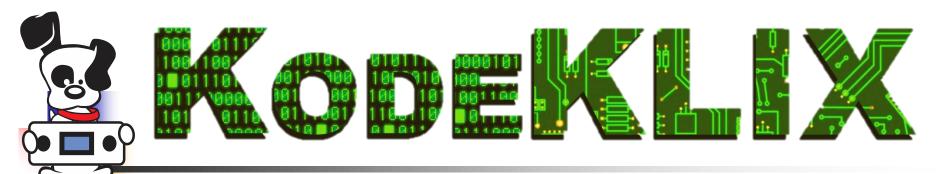




Servo Attachments...

- Three servo arms are provided in the kit
- The arms are held in place by a screw
- The different arms control how the servo's motion is translated into actions;
 - Mount directly to the swing arm, or
 - Connect via a paperclip/wire for push-pull control





www.kodeklix.com **Coding for Young Engineers**

Nick Coplin **Creator:**

www.kodeklix.com/snapcpu4stem/ Projects:

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